

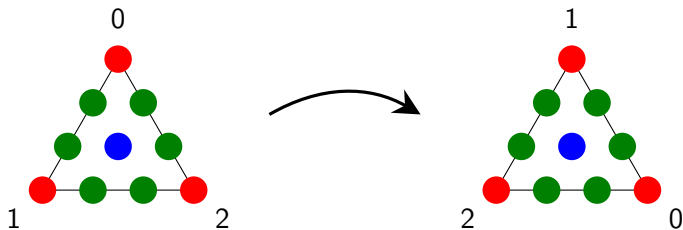
Symmetry in Finite Element Exterior Calculus

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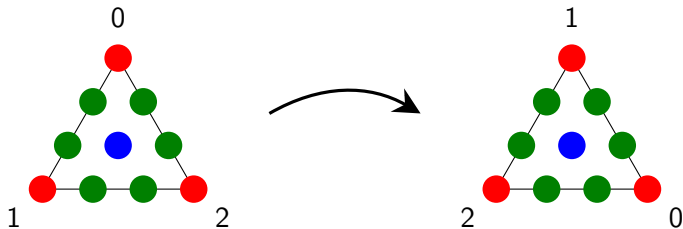
April 8–9, 2022

Symmetry of Scalar Elements



$$\mathcal{P}_3\Lambda^0(T^2) = \langle \lambda_0^3, \lambda_1^3, \lambda_2^3, \lambda_1^2\lambda_2, \lambda_2^2\lambda_1, \lambda_2^2\lambda_0, \lambda_0^2\lambda_2, \lambda_0^2\lambda_1, \lambda_1^2\lambda_0, \lambda_0\lambda_1\lambda_2 \rangle.$$

Symmetry of Scalar Elements



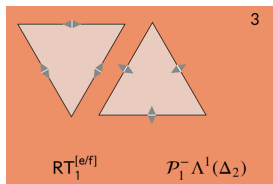
$$\mathcal{P}_3\Lambda^0(T^2) = \langle \lambda_0^3, \lambda_1^3, \lambda_2^3, \lambda_1^2\lambda_2, \lambda_2^2\lambda_1, \lambda_2^2\lambda_0, \lambda_0^2\lambda_2, \lambda_0^2\lambda_1, \lambda_1^2\lambda_0, \lambda_0\lambda_1\lambda_2 \rangle.$$

- When computing matrix of, e.g., $a(u, v) = \int_{T^2} \nabla u \cdot \nabla v$, can exploit sixfold symmetry of T^2 to compute fewer entries.

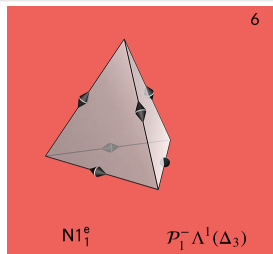
$$\begin{aligned} a(\lambda_0^3, \lambda_1^2\lambda_2) &= a(\lambda_0^3, \lambda_2^2\lambda_1) \\ &= a(\lambda_1^3, \lambda_2^2\lambda_0) = a(\lambda_1^3, \lambda_0^2\lambda_2) \\ &= a(\lambda_2^3, \lambda_0^2\lambda_1) = a(\lambda_2^3, \lambda_1^2\lambda_0) \end{aligned}$$

Symmetry of Vector Elements

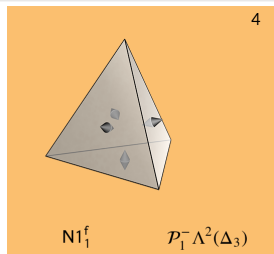
Whitney Elements



$$\langle \lambda_1 d\lambda_2 - \lambda_2 d\lambda_1, \\ \lambda_2 d\lambda_0 - \lambda_0 d\lambda_2, \\ \lambda_0 d\lambda_1 - \lambda_1 d\lambda_0 \rangle.$$



$$\langle \lambda_1 d\lambda_2 - \lambda_2 d\lambda_1, \\ \lambda_2 d\lambda_0 - \lambda_0 d\lambda_2, \\ \lambda_0 d\lambda_1 - \lambda_1 d\lambda_0, \\ \lambda_0 d\lambda_3 - \lambda_3 d\lambda_0, \\ \lambda_1 d\lambda_3 - \lambda_3 d\lambda_1, \\ \lambda_2 d\lambda_3 - \lambda_3 d\lambda_2 \rangle.$$

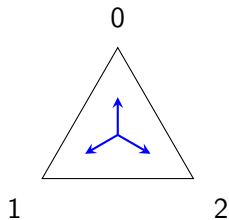


$$\langle \lambda_1 d\lambda_2 \wedge d\lambda_3 \\ + \lambda_2 d\lambda_3 \wedge d\lambda_1 \\ + \lambda_3 d\lambda_1 \wedge d\lambda_2, \\ \dots, \\ \lambda_0 d\lambda_1 \wedge d\lambda_2 \\ + \lambda_1 d\lambda_2 \wedge d\lambda_0 \\ + \lambda_2 d\lambda_0 \wedge d\lambda_1 \rangle$$

Geometric symmetry \Rightarrow basis symmetry (up to sign).

Symmetry of Vector Elements

Lack of Symmetric Bases



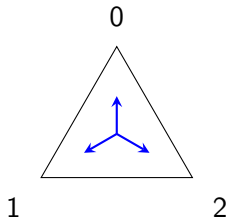
$$\mathcal{P}_0\Lambda^1(T^2)$$

$$= \langle d\lambda_0, d\lambda_1, d\lambda_2 \rangle,$$

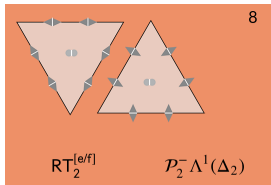
$$d\lambda_0 + d\lambda_1 + d\lambda_2 = 0$$

Symmetry of Vector Elements

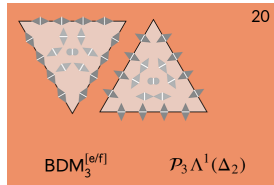
Lack of Symmetric Bases



$$\mathcal{P}_0 \Lambda^1(T^2)$$
$$= \langle d\lambda_0, d\lambda_1, d\lambda_2 \rangle,$$
$$d\lambda_0 + d\lambda_1 + d\lambda_2 = 0$$



$$\langle \lambda_1^2 d\lambda_2 - \lambda_1 \lambda_2 d\lambda_1,$$
$$\lambda_2^2 d\lambda_1 - \lambda_1 \lambda_2 d\lambda_2,$$
$$\dots,$$
$$\lambda_0^2 d\lambda_1 - \lambda_0 \lambda_1 d\lambda_0,$$
$$\lambda_1^2 d\lambda_0 - \lambda_0 \lambda_1 d\lambda_1,$$
$$\lambda_0 \lambda_1 d\lambda_2 - \lambda_0 \lambda_2 d\lambda_1,$$
$$\lambda_1 \lambda_2 d\lambda_0 - \lambda_0 \lambda_1 d\lambda_2,$$
$$\lambda_0 \lambda_2 d\lambda_1 - \lambda_1 \lambda_2 d\lambda_0 \rangle.$$



$$\langle \dots,$$
$$\dots,$$
$$\lambda_0 \lambda_1 \lambda_2 d\lambda_0,$$
$$\lambda_0 \lambda_1 \lambda_2 d\lambda_1,$$
$$\lambda_0 \lambda_1 \lambda_2 d\lambda_2 \rangle.$$

Theorem (if: Licht, 2019; only if: YBK, 2021)

The following spaces have symmetry-invariant bases up to sign if and only if the corresponding condition holds.

$$\begin{array}{lll} \mathcal{P}_r \Lambda^1(T^2) & \text{if and only if} & r \notin 3\mathbb{N}_0, \\ \mathcal{P}_r^- \Lambda^1(T^2) & \text{if and only if} & r \notin 3\mathbb{N}_0 + 2. \end{array}$$

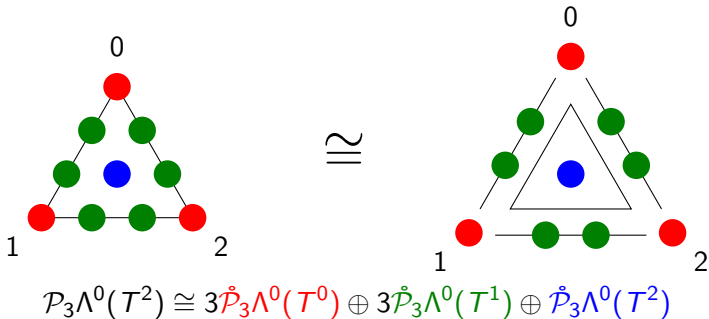
Theorem (YBK, 2021)

The following spaces have symmetry-invariant bases up to sign if and only if the corresponding condition holds.

$$\begin{array}{lll} \mathcal{P}_r \Lambda^1(T^3) & \text{always,} & \\ \mathcal{P}_r^- \Lambda^1(T^3) & \text{if and only if} & r \notin 3\mathbb{N}_0 + 2, \\ \mathcal{P}_r \Lambda^2(T^3) & \text{always,} & \\ \mathcal{P}_r^- \Lambda^2(T^3) & \text{always.} & \end{array}$$

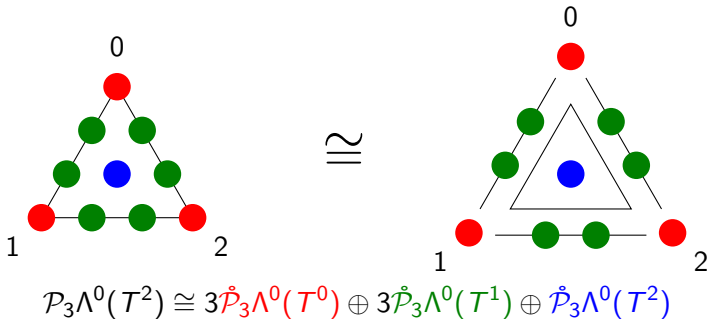
Methods

Recursion



Methods

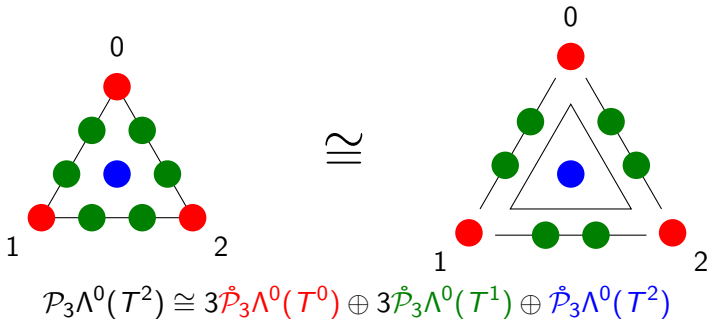
Recursion



$$\langle \lambda_0^3 \rangle \oplus \langle \lambda_1^3 \rangle \oplus \langle \lambda_2^3 \rangle \\ \oplus \langle \lambda_1^2 \lambda_2, \lambda_2^2 \lambda_1 \rangle \oplus \langle \lambda_2^2 \lambda_0, \lambda_0^2 \lambda_2 \rangle \oplus \langle \lambda_0^2 \lambda_1, \lambda_1^2 \lambda_0 \rangle \oplus \langle \lambda_0 \lambda_1 \lambda_2 \rangle$$

Methods

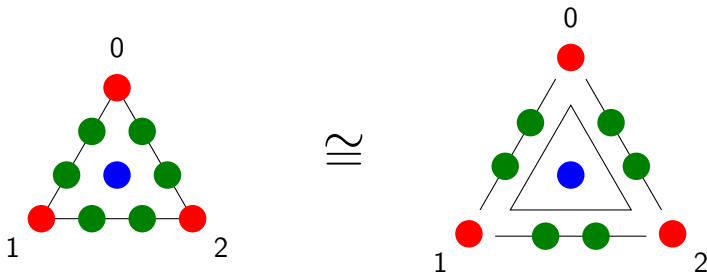
Recursion



$$\begin{aligned} & \langle \lambda_0^3 \rangle \oplus \langle \lambda_1^3 \rangle \oplus \langle \lambda_2^3 \rangle \\ & \oplus \langle \lambda_1^2 \lambda_2, \lambda_2^2 \lambda_1 \rangle \oplus \langle \lambda_2^2 \lambda_0, \lambda_0^2 \lambda_2 \rangle \oplus \langle \lambda_0^2 \lambda_1, \lambda_1^2 \lambda_0 \rangle \oplus \langle \lambda_0 \lambda_1 \lambda_2 \rangle \\ \cong & \langle \lambda_0^2 \rangle \oplus \langle \lambda_1^2 \rangle \oplus \langle \lambda_2^2 \rangle \\ & \oplus \langle \lambda_1 ds, \lambda_2 ds \rangle \oplus \langle \lambda_0 ds, \lambda_2 ds \rangle \oplus \langle \lambda_0 ds, \lambda_1 ds \rangle \oplus \langle 1 dA \rangle \end{aligned}$$

Methods

Recursion



$$\begin{aligned}\mathcal{P}_3 \Lambda^0(T^2) &\cong 3\dot{\mathcal{P}}_3 \Lambda^0(T^0) \oplus 3\dot{\mathcal{P}}_3 \Lambda^0(T^1) \oplus \dot{\mathcal{P}}_3 \Lambda^0(T^2) \\ &\cong 3\mathcal{P}_2 \Lambda^0(T^0) \oplus 3\mathcal{P}_1 \Lambda^1(T^1) \oplus \mathcal{P}_0 \Lambda^2(T^2)\end{aligned}$$

$$\langle \lambda_0^3 \rangle \oplus \langle \lambda_1^3 \rangle \oplus \langle \lambda_2^3 \rangle$$

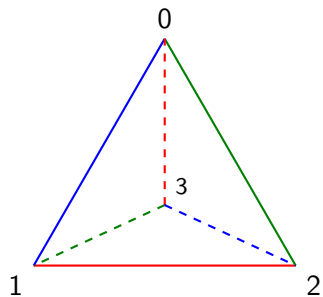
$$\oplus \langle \lambda_1^2 \lambda_2, \lambda_2^2 \lambda_1 \rangle \oplus \langle \lambda_2^2 \lambda_0, \lambda_0^2 \lambda_2 \rangle \oplus \langle \lambda_0^2 \lambda_1, \lambda_1^2 \lambda_0 \rangle \oplus \langle \lambda_0 \lambda_1 \lambda_2 \rangle$$

$$\cong \langle \lambda_0^2 \rangle \oplus \langle \lambda_1^2 \rangle \oplus \langle \lambda_2^2 \rangle$$

$$\oplus \langle \lambda_1 ds, \lambda_2 ds \rangle \oplus \langle \lambda_0 ds, \lambda_2 ds \rangle \oplus \langle \lambda_0 ds, \lambda_1 ds \rangle \oplus \langle 1 dA \rangle$$

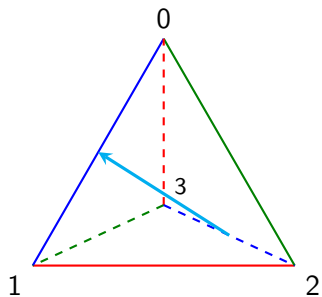
Methods

Tetrahedron Basis



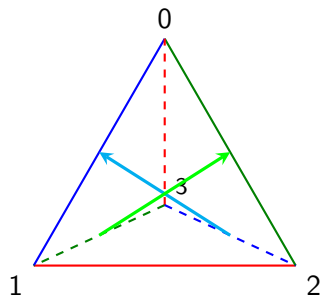
Methods

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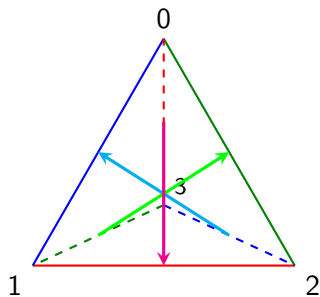
Methods

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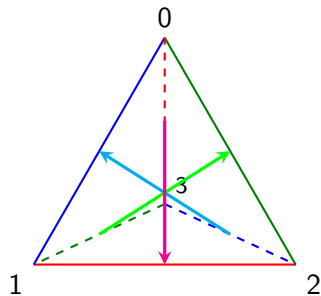
Methods

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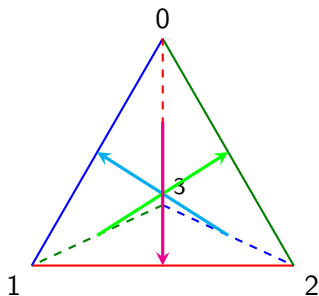
$$\mathcal{P}_0\Lambda^1(T^3)$$

$$= \langle d\lambda_0 + d\lambda_1 - d\lambda_2 - d\lambda_3, \\ d\lambda_0 + d\lambda_2 - d\lambda_1 - d\lambda_3, \\ d\lambda_1 + d\lambda_2 - d\lambda_0 - d\lambda_3 \rangle$$

$$=: \langle \alpha, \beta, \gamma \rangle.$$

Methods

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$$\begin{aligned} & \mathcal{P}_0\Lambda^1(T^3) \\ = & \langle d\lambda_0 + d\lambda_1 - d\lambda_2 - d\lambda_3, \\ & d\lambda_0 + d\lambda_2 - d\lambda_1 - d\lambda_3, \\ & d\lambda_1 + d\lambda_2 - d\lambda_0 - d\lambda_3 \rangle \\ =: & \langle \alpha, \beta, \gamma \rangle. \end{aligned}$$

$$\begin{aligned} & \mathcal{P}_2\Lambda^1(T^3) \\ = & \mathcal{P}_2\Lambda^0(T^3) \otimes \mathcal{P}_0\Lambda^1(T^3) \\ = & \langle \lambda_0^2\alpha, \lambda_0^2\beta, \lambda_0^2\gamma, \\ & \lambda_1^2\alpha, \lambda_1^2\beta, \lambda_1^2\gamma, \\ & \lambda_2^2\alpha, \lambda_2^2\beta, \lambda_2^2\gamma, \\ & \lambda_3^2\alpha, \lambda_3^2\beta, \lambda_3^2\gamma, \\ & \lambda_0\lambda_1\alpha, \lambda_0\lambda_1\beta, \lambda_0\lambda_1\gamma, \\ & \lambda_0\lambda_2\alpha, \lambda_0\lambda_2\beta, \lambda_0\lambda_2\gamma, \\ & \lambda_0\lambda_3\alpha, \lambda_0\lambda_3\beta, \lambda_0\lambda_3\gamma, \\ & \lambda_1\lambda_2\alpha, \lambda_1\lambda_2\beta, \lambda_1\lambda_2\gamma, \\ & \lambda_1\lambda_3\alpha, \lambda_1\lambda_3\beta, \lambda_1\lambda_3\gamma, \\ & \lambda_2\lambda_3\alpha, \lambda_2\lambda_3\beta, \lambda_2\lambda_3\gamma \rangle. \end{aligned}$$

Representations of $\mathbb{Z}/3$

- The 1D representation **1** where $\mathbb{Z}/3$ acts trivially.
- The 2D representation **2** where $\mathbb{Z}/3$ acts by 120° rotations.
- The 3D representation **3** where $\mathbb{Z}/3$ acts by permuting the coordinates.
 - **3** \cong **1** \oplus **2** because $\langle(1, 1, 1)\rangle$ is an invariant subspace.

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Invariant bases

1 and **3** have symmetry-invariant bases, but **2** does not.

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Proposition

A representation $V \cong m\mathbf{1} \oplus n\mathbf{2}$ has a $\mathbb{Z}/3$ -invariant basis up to sign if and only if $m \geq n$.

Thank You and References



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Yakov Berchenko-Kogan.

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